

NX Nastran – Basic

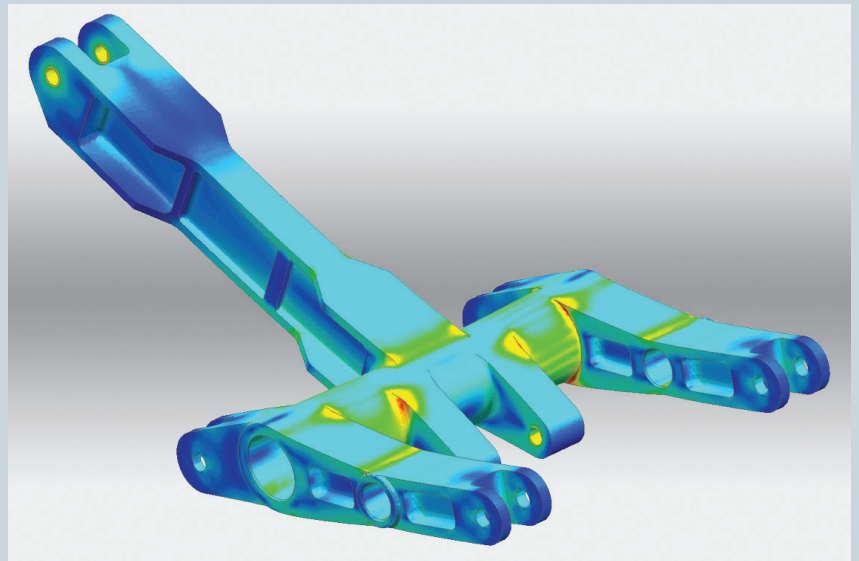
The core structural analysis FEA solver used by leading product development firms for over 40 years

Benefits

- Reduce risk by using simulation to save time and cost compared to physical test cycles
- Accelerate innovation through rapid iteration and numerous “what-if” studies
- Investigate product performance virtually under all possible operating conditions, including thermally-influenced operating conditions

Summary

NX™ Nastran® – Basic is the core subset of NX Nastran software and includes a robust suite of linear statics, normal modes, buckling analyses, heat transfer and basic nonlinear capabilities. NX Nastran – Basic can play a key role in your virtual product development process by providing the most widely used CAE solutions for digital prototyping and simulation of product functional performance.



NX Nastran – Basic provides you access to a broad library of finite element types and material models, robust manipulation of load cases, along with several efficient solution sequences for linear statics, buckling and normal modes analyses on models of unlimited size. A heat transfer capability provides solutions to steady-state and transient thermal analysis and design problems. NX Nastran – Basic’s nonlinear capability enables users to include large deformations and non-linear materials in their analyses.

NX

Answers for industry.

SIEMENS

NX Nastran – Basic

Solution types supported by NX Nastran – Basic

| SOL Number | SOL Name | Description |
|------------|----------|--|
| 101 | SESTATIC | Linear statics |
| 103 | SEMODES | Normal modes |
| 105 | SEBUCKL | Buckling |
| 106 | NLSTATIC | Nonlinear or linear statics |
| 114 | CYCSTATX | Cyclic statics |
| 115 | CYCMODE | Cyclic normal modes |
| 116 | CYCBUCKL | Cyclic buckling |
| 129 | NLTRAN | Nonlinear or linear transient response |
| 153 | NLSCSH | Static structural and/or steady state heat transfer analysis |
| 159 | NLTCSH | Transient structural and/or transient heat transfer analysis |

Start simply, add as your needs evolve

NX Nastran – Basic will allow you to initiate digital simulation into your product development process by providing access to a broad library of finite element types and material models, robust manipulation of load cases, along with several efficient solution sequences for linear statics (including buckling) and normal modes analyses on models of unlimited size. You can also perform sensitivity studies based on these analysis types. NX Nastran's powerful analysis capabilities will provide you with the tools you need for:

- Linear statics, including inertia relief
- Normal modes
- Buckling
- Design sensitivity (statics, modes, buckling)
- Model checkout
- Heat transfer
- Basic nonlinear
- Coupled structure/acoustic modes

NX Nastran – Basic includes a complete element library including 1D, 2D and 3D low- and higher-order elements; scalar and special elements including spot weld as well as p-elements (that can be combined with other elements).

Table 1 – Element types supported by NX Nastran – Basic

| Element type | Element name | Description |
|---------------|--|---|
| Scalar | ELAS | Scalar spring (several variations) |
| | MASS | Scalar mass (several variations) |
| 1D | BAR | Simple beam element |
| | BEAM | Complex beam element including shear center offset and variable cross section |
| | BEND | Curved beam, pipe or elbow |
| | ROD | Rod element tension-compression-torsion element |
| | CONROD | |
| 2D | TUBE | |
| | QUAD4 | Quadrilateral plate with membrane-bending or plane strain behavior |
| | QUAD8 | Higher-order quadrilateral shell element |
| | QUADR | Quadrilateral membrane or shell |
| | SHEAR | Shear panel |
| | TRIA3 | Triangular plate with membrane-bending or plain strain behavior |
| | TRIA6 | Higher-order triangular shell element |
| | TRIA | Triangular membrane or shell |
| | CPLSTN3 | Plane strain triangular element connection |
| | CPLSTN6 | Plane strain high-order triangular element connection |
| | CPLSTN4 | Plane strain quadrilateral element connection |
| | CPLSTN8 | Plane strain high-order quadrilateral element connection |
| | CPLSTS3 | Plane stress triangular element connection |
| | CPLSTS6 | Plane stress high-order triangular element connection |
| CPLSTS4 | Plane stress quadrilateral element connection | |
| CPLSTS8 | Plane stress high-order quadrilateral element connection | |
| 3D | HEXA | Six-sided solid element with 8-20 grid points |
| | PENTA | Five-sided solid element with 6-15 grid points |
| | TETRA | Four-sided solid element with 4-10 grid points |
| | PYRAMID | 5-sided solid element with 5-13 grid points |
| Rigid | RBAR | Rigid bar element |
| | RBE1 | Rigid body connected to an arbitrary number of grid points |
| | RBE2 | Rigid body with independent DOFs at a grid point and dependent DOFs at an arbitrary number of grid points |
| | RROD | Pin-ended rigid rod |
| | RTRPLT | Rigid triangular plate |
| Interpolation | RBE3 | Defines motion of a reference point as the weighted average of the motions at a set of grid points |
| | RSPLINE | Multipoint constraints for the interpolation of displacements at grid points |
| Composites | BEAM | Complex beam element |
| | QUAD4 | Quadrilateral plate |
| | QUAD8 | Higher-order quadrilateral plate |
| | QUADR | Quadrilateral plate |
| | TRIA3 | Triangular plate |
| | TRIA6 | Higher-order triangular plate |
| | TRIAR | Triangular plate |
| | CHEXA | Six-sided solid element with 8-20 grid points |
| CPENTA | Five-sided solid element with 6-15 grid points | |
| p-elements | HEXA | Six-sided solid element with 8-20 grid points |
| | PENTA | Five-sided solid element with 6-15 grid points |
| | TETRA | Four-sided solid element with 4-10 grid points |

Table 1 (continued)

| Element type | Element name | Description |
|--------------|--------------|---|
| Axisymmetric | CONEAX | Conical shell |
| | TRIAX6 | Triangular cross section ring |
| | CTRAX3 | Triangle |
| | CTRAX6 | Higher order triangle |
| | CQUADX4 | Quad |
| | CQUADX8 | Higher order quad |
| Crack tip | CRAC2D | Two-dimensional crack tip element |
| | CRAC3D | Three-dimensional crack tip element |
| General | CONM1 | 6-b-6 symmetric mass matrix |
| | CONM2 | Concentrated mass with offsets |
| | DMI | Direct matrix input |
| | GENEL | General element |
| Weld | CWELD | Weld connection element |
| Fastener | CFAST | Fastener element for shell patch connection |

NX Nastran – Basic provides a full range of material models: isotropic, orthotropic, anisotropic and temperature-dependent. It also allows for easy combination (or addition) of load cases, such as point, line and surface loads on elements; loads applied directly to geometry; thermal loads; enforced deformation; and weighted combinations of each type.

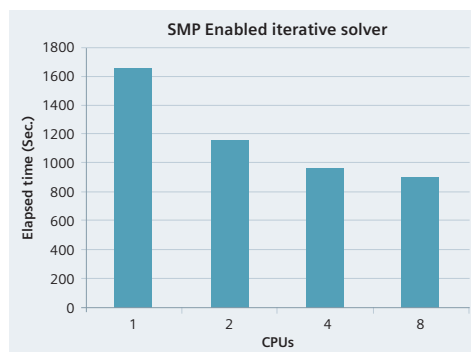
Table 2 – Static loading types in NX Nastran – Basic

| Load type | Load name | Description |
|--------------|-----------|--|
| Point | FORCE | Concentrated force (several variations) |
| | MOMENT | Concentrated moment (several variations) |
| Curve | GMLOAD | Load distributed along a geometric curve |
| | PLOAD1 | Concentrated, uniform or linear load applied to 1D elements |
| Edge | PLOADE1 | Edge Load on Plane Strain and Plane Stress Elements |
| Surface | GMLOAD | Load distributed along a geometric surface |
| | PLOAD | Pressure load applied to 2D elements or the face of 3D elements (several variations) |
| Volume | GRAV | Steady-state acceleration vectors |
| | RFORCE | Angular velocity or acceleration |
| | ACCEL | Spatial varying acceleration load |
| Bolt preload | BOLTFOR | Bolt preload applied to beam elements |
| Enforced | GMBC | Enforced displacements for geometry motion (curves motion and surfaces) |
| | GMSPC | Constraints applied to geometry |
| | SPC | Constraints applied to grid points (several variations) |
| Thermal | TEMP | Temperatures applied to grid points (several variations) |
| | TEMPP1 | 2D element temperature field |
| | TEMPRB | 1D element temperature field |

Table 2 (continued)

| Load type | Load name | Description |
|---------------------|-----------|--------------------------|
| Axisymmetric | FORCEAX | Concentrated force |
| | MOMAX | Concentrated moment |
| | PLOAD1X | Surface traction |
| | PRESAX | Pressure loading |
| | SPCAX | Constraints |
| | TEMPAX | Applied temperatures |
| General | DMI | Direct matrix input |
| Combination | LOAD | Combine load sets |
| Non-structural mass | NSM | Non-structural mass sets |

NX Nastran – Basic provides several non-elemental approaches for connecting meshes and transferring loads. This can greatly simplify modeling procedures.



SMP enabled iterative solver reduces linear static solution time by as much as 45 percent on 8 CPUs for higher-order solid models.

Table 3 – Non-elemental mesh connections in NX Nastran – Basic

| Type | Name | Description |
|------------|--------|---|
| Constraint | MPC | Constraint equations used to connect specified degrees-of-freedom |
| | RSSCON | Constraint relation to connect shell to solid elements |
| Contact | BSURF | A set of shell element faces that define a contact surface |
| | BSURFS | A set of solid element faces that define a contact surface |
| | BCTSET | Pairs of contact surfaces that can contact in a linear static solution |
| Glue | BSURF | A set of shell element faces that define a glue surface |
| | BSURFS | A set of solid element faces that define a glue surface |
| | BGSET | Pairs of glue surfaces that are in connection in any solution type |
| | BLSEG | Defines a glue or contact edge region, or a curve for slideline contact |

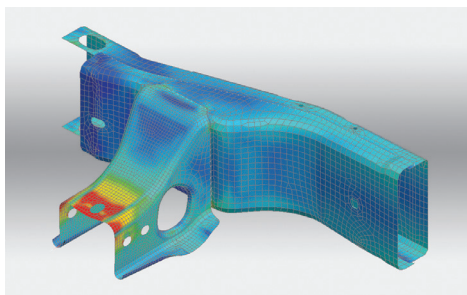
Additional capabilities for linear static and Eigenvalue solutions

Linear static solutions

- Edge-to-surface contact to glue the edges of shell elements to the faces of solid or shell elements
- Surface-to-surface contact for shell and solid elements
- Edge-to-edge glue between the edges of shell, axisymmetric, plane stress and plane strain elements
- Inertia relief for unrestrained models
- Shared memory parallel (SMP) processing enabled element-based iterative solver for very fast solutions of tetrahedron meshed models
- Bolt preload effects
- Thermal expansion for rigid elements

Normal mode solutions

- Lanczos
- Residual vectors for residual flexibility
- Differential stiffness effects
- Unconstrained model solutions
- Solution about a contact condition
- Export modes to ADAMS or RecurDyn



Design sensitivity analysis for assessing design changes

- Shape and sizing design variables
- Preset objective and constraints
- Weight, volume
- Element stress, strain, force
- Displacement, rotation, reaction force
- Normal modes Eigenvalue
- Buckling load factor
- Composites: lamina strain, force and failure index
- User-defined objective and constraints
- Efficient handling of hundreds of design variables, constraints and load cases
- buckling in a single run

Efficient solvers

- Sparse matrix solvers for faster speed and minimal disk space usage
- Automatic internal resequencing for bandwidth reduction
- Restarts to take advantage of previously computed solutions

Steady-state and transient thermal analysis

NX Nastran – Basic provides heat transfer solutions to steady-state and transient thermal analysis design problems. This capability may also be used in combination with NX Nastran structural analyses to perform thermal stress analysis.

If changes in temperature and the flow of heat within your product could affect its performance, heat transfer should play a key role in your digital simulation process. Heat transfer can span the full range from system-level analysis of global energy balances to the detailed analysis associated with temperature and thermal stress limit levels. It allows you to investigate linear or nonlinear problems, steady-state or transient effects, as well as all three types of heat transfer (conduction, convection and radiation), displaying the characteristics associated with each.

Heat conduction

- Temperature-dependent conductivity
- Temperature-dependent specific heat
- Anisotropic thermal conductivity
- Latent heat of phase change
- Temperature-dependent internal heat generation

- Weighted temperature gradient-dependent internal heat generation
- Time-dependent internal heat generation

Free convection boundaries

- Temperature-dependent heat transfer coefficient
- Weighted temperature gradient-dependent heat transfer coefficient
- Time-dependent heat transfer coefficient
- Nonlinear functional forms
- Weighted film temperatures

Forced convection

- Tube fluid flow field relationships
- Temperature-dependent fluid viscosity, conductivity and specific heat
- Time-dependent mass flow rate
- Temperature-dependent mass flow rate
- Weighted temperature gradient-dependent mass flow rate

Radiation to space

- Temperature-dependent and wavelength-dependent emissivity
- Diffuse 3D view factor calculations with self and third-body shadowing
- Adaptive view factor calculations
- Net view factors
- User-supplied exchange factors
- Radiation matrix control
- Multiple radiation enclosures

Applied heat loads

- Direction and surface normal heat flux
- Grid point nodal power
- Temperature-dependent and weighted gradient-dependent heat flux
- Time-dependent heat flux
- Temperature boundary conditions
- Temperature initial conditions

Basic nonlinear analysis

NX Nastran – Basic enables you to analyze models with geometric nonlinearities; that is, large deformations or with material nonlinearities. Point-to-point contact nonlinearity can also be simulated. This basic nonlinear capability allows users to evaluate whether the small displacement and linear material assumptions used in linear analysis are accurate.

Geometric nonlinear behavior

- Large deformations
- Large strain for hyperelastic material
- Snap-through analysis (post-buckling)

Material nonlinear behavior

- Plasticity
- Hyperelasticity
- Thermoelasticity
- Viscoelasticity (creep)

Automated solution methods – statics

- Load control method
- Displacement control method
- Adaptive load increment

Other features

- Static and transient solutions
- Restart analysis
- Identical element types in linear and nonlinear analysis
- Point-to-point contact with gap elements

Contact
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